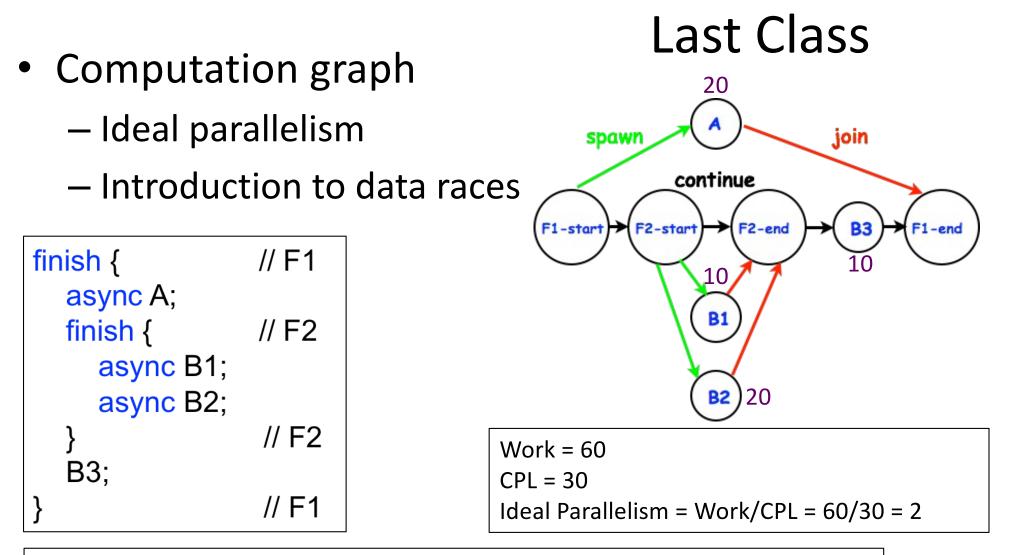
#### **CSE502: Foundations of Parallel Programming**

### Lecture 07: Greedy Scheduling of Computation Graph on a Fixed Number of Processors

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A data race occurs on location L in a program execution with computation graph CG if there exist steps (nodes) S1 and S2 in CG such that:

- 1. S1 does not depend on S2 and S2 does not depend on S1, i.e., S1 and S2 can potentially execute in parallel, and
- 2. Both S1 and S2 read or write L, and at least one of the accesses is a write.

## Today's Class

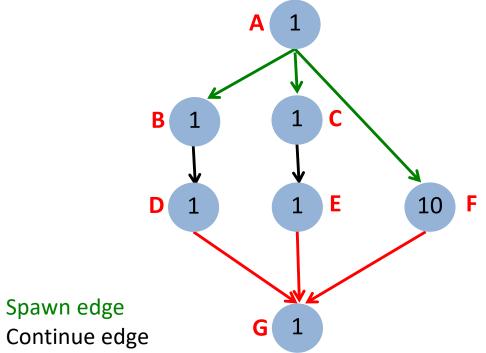
- Greedy scheduling of computation graph on fixed number of processors
  - Lower and upper bound on execution time
- Thread pool

## Greedy Schedule

- A greedy schedule is one that never leaves a processor idle when one or more nodes are ready for execution
- A node is ready for execution if all its predecessors have been executed
- Observations
  - T<sub>1</sub> = WORK(G), for all greedy schedules
  - $-T_{\infty} = CPL(G)$ , for all greedy schedules
- where T<sub>P</sub> = execution time of a schedule for computation graph G on P processors

# Scheduling of a Computation Graph on a fixed number of processors: Example

A(); // 1 units finish { async { B(); // 1 units D(); // 1 units async { C(); // 1 units E(); // 1 units async F(); // 10 units // 1 units G();



- Join edge
- Node label = time(N), for all nodes N in the graph
- CPL (Graph) = 12
- Work (Graph) = 16
- Ideal Parallelism = 16/12 = 1.33

#### Lower Bounds on Execution Time of Greedy Schedules

Start Proc1 Proc2 **Best** possible execution Time time of this computation 0 graph on two processors 1 2 3 4 1 С Β 5 6 10 Ε F D 1 7 8 9 10 G 1 11 12

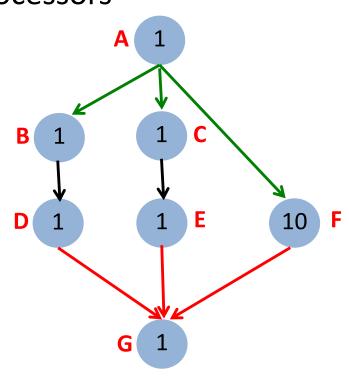
Lower Bounds on Execution Time of Greedy Schedules

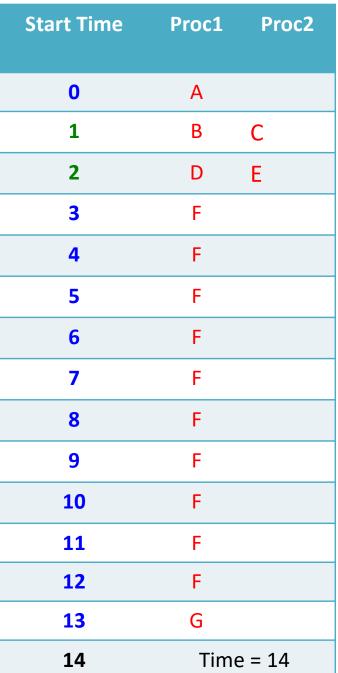
- Let T<sub>P</sub> = execution time of a schedule for computation graph G on P processors

   Can be different for different schedules
- Lower bounds for all greedy schedules
  - Capacity bound:  $T_P \ge WORK(G)/P$
  - Critical path bound:  $T_P \ge CPL(G)$
- Putting them together
  - $-T_{P} \ge max(WORK(G)/P, CPL(G))$

#### Upper Bound on Execution Time of Greedy Schedules Start Time Proc

 Worst possible execution time of this computation graph on two processors





### Upper Bound on Execution Time of Greedy Schedules

- Define a time step to be complete if ≥ P nodes are ready at that time, or incomplete otherwise
  - $#Steps_{Complete} \leq WORK(G)/P$
  - $#Steps_{Incomplete} \le CPL(G)$
  - $-T_P = #Steps_{Complete} + #Steps_{Incomplete}$
  - $-T_{P} \leq WORK(G)/P + CPL(G)$ 
    - Theorem [Graham'68, Brent'74]

Start Time	Proc1	Proc2
0	Α	
1	В	С
2	D	E
3	F	
4	F	
5	F	
6	F	
7	F	
8	F	
9	F	
10	F	
11	F	
12	F	
13	G	
14	Time = 14	

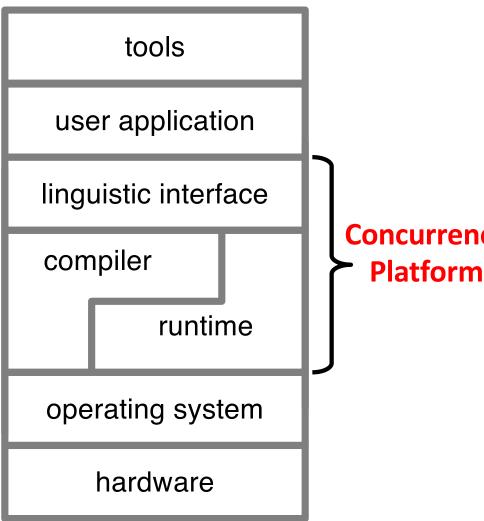
## Today's Class

 Greedy scheduling of computation graph on fixed number of processors

Lower and upper bound on execution time



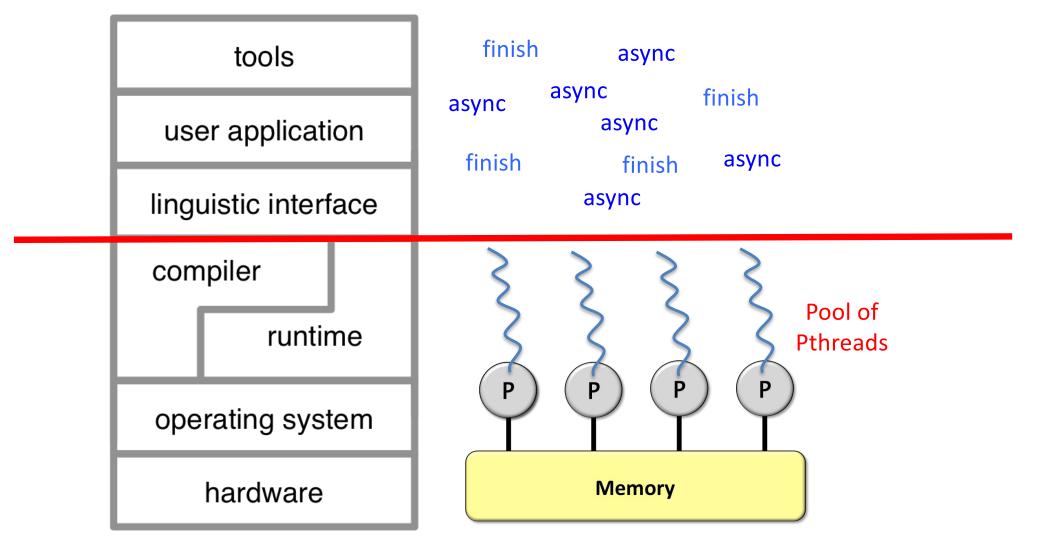
### **Concurrency Platforms (Recap Lec04)**



A concurrency platform should provide:

- an interface for specifying the *logical parallelism* of the computation;
- Concurrency a runtime layer to
   Platform automate scheduling and synchronization; and
  - guarantees of performance and resource utilization competitive with hand-tuned code.

## **Thread Pool in Concurrency Platforms**



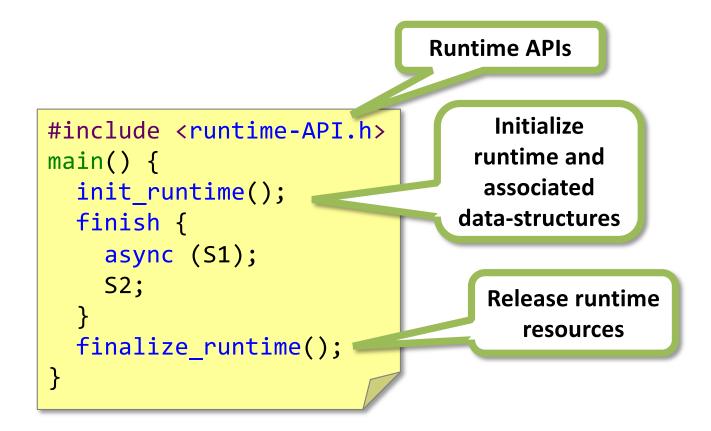
In this course we are only going to consider the case where a thread pool has total number of threads (Pthreads) equal to total number of available cores © Vivek Kumar

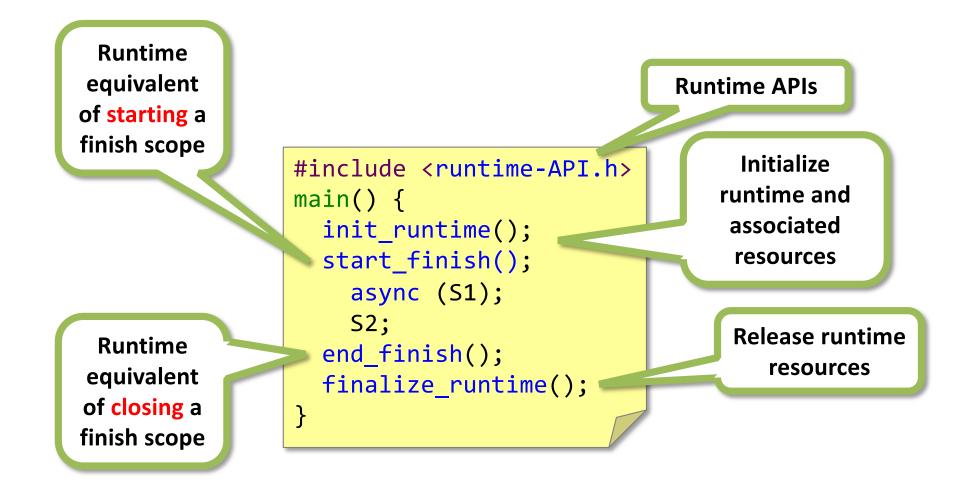
### Thread Pool in Concurrency Platforms

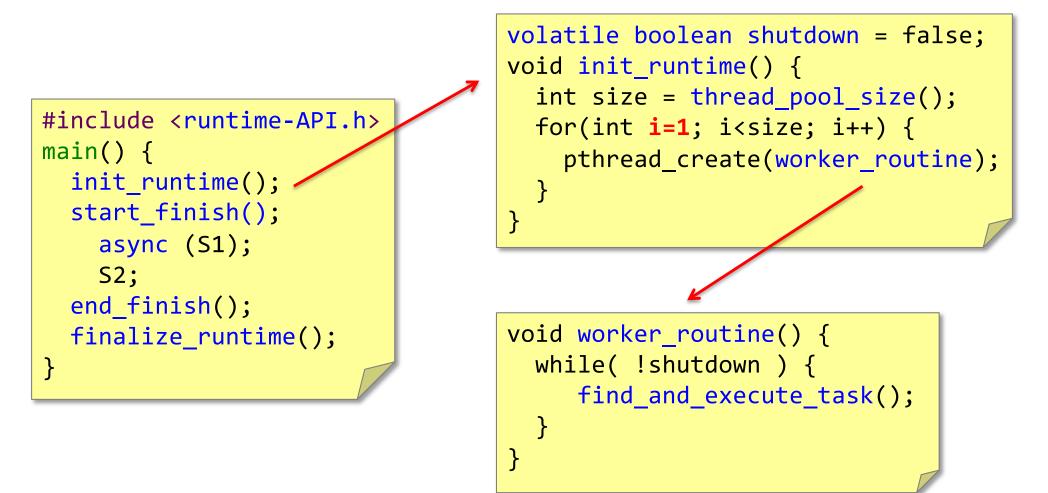
- A Key component in any concurrency platform that relieves the user from the complexity of mapping tasks to threads (e.g., Pthreads) to achieve maximum performance on a given number of processors (or cores)
  - Sneak peek: thread pools does not restricts to shared-memory platform (multicore processor), but can also be extended to distributed memory platform (supercomputer)

### Mapping the Linguistic Interface to Thread Pool Runtime

- Compiler based runtimes
  - Cilk, X10, TryCatchWS
  - User code translated to runtime code and then compiled using a native compiler (e.g., gcc)
  - Compiler maintenance is a costly affair and it is not so easy to use new features from mainstream languages
  - Using standard debugger (e.g., gdb) is not possible as the line number information inside the symbol table is w.r.t. the compiler generated code and not w.r.t. the user written code
  - However, compiler based approach provide several opportunities for code optimizations and doing smart things
- Library based runtimes Our focus
  - Java fork/join framework, HClib, HJlib
  - Removes all the drawbacks of a compiler based approach







Note: here the workers are continuously spinning, but in some implementation they might sleep if no tasks are available

```
#include <runtime-API.h>
main() {
    init_runtime();
    start_finish();
    async (S1);
    S2;
    end_finish();
    finalize_runtime();
}
```

```
volatile int finish_counter = 0;
void start_finish() {
  finish_counter = 0; //reset
}
```

Note: in case of nested finish (e.g., Fibonacci), we need a better way to manage finish scopes. Recall, in Fibonacci every fib(n) call created a new finish, which ultimately creates a tree of finishes

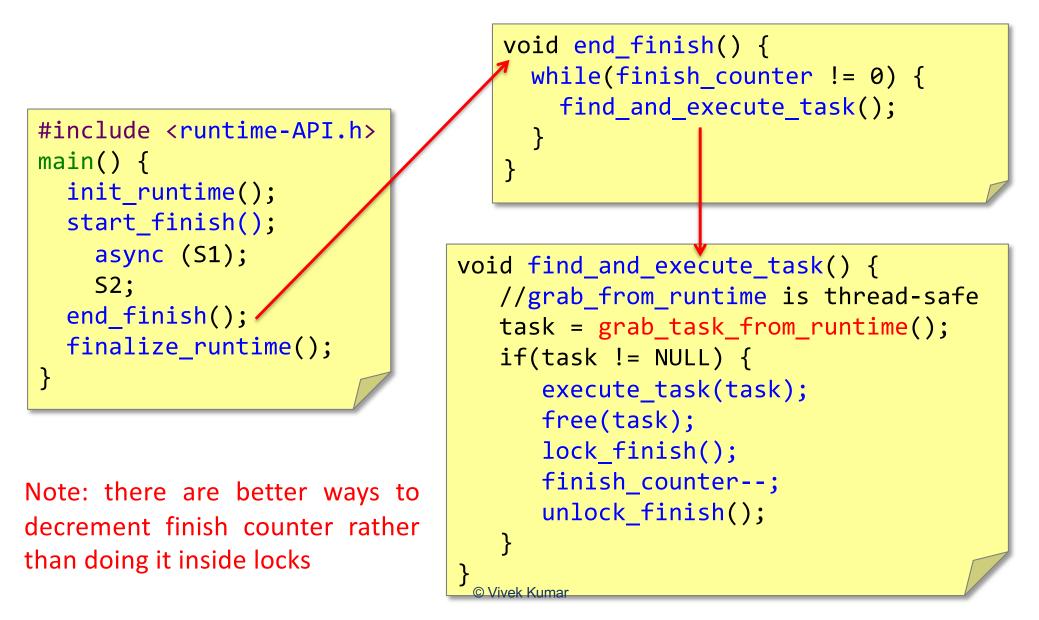
```
#include <runtime-API.h>
main() {
    init_runtime();
    start_finish();
    async (S1);
    S2;
    end_finish();
    finalize_runtime();
}
```

Note: Runtime stores pointer to the tasks passed in the async. To ensure valid pointer during task execution, we heap allocate the task and store pointer to the task on heap.

```
void async(task) {
    lock_finish();
    finish_counter++;//concurrent access
    unlock_finish();
    // copy task on heap
    void* p = malloc(task_size);
    memcpy(p, task, task_size);
    //thread-safe push_task_to_runtime
    push_task_to_runtime(&p);
    return;
```

Note: there are better ways to increment finish counter rather than doing it inside locks

}



```
#include <runtime-APT.h>
main() {
  init_runtime();
  start_finish();
                               void finalize_runtime() {
    async (S1);
                                  //all spinning workers
    S2;
                                  //will exit worker_routine
  end finish();
                                  shutdown = true;
  finalize_runtime();
                                  int size = thread_pool_size();
}
                                  // master waits for helpers to join
                                  for(int i=1; i<size; i++) {</pre>
                                    pthread_join(thread[i]);
                                  }
                               }
```

### How to Store Tasks in Runtime ?

- push\_task\_to\_runtime()
- grab\_task\_from\_runtime()

Data-structures for storing tasks in a thread pool based runtime plays a very important role in determining the scalability and performance of the runtime

#### Next Lecture

• Work-sharing and work-stealing task scheduling