

Lecture 07: Controlling Task Granularity

Vivek Kumar

Computer Science and Engineering

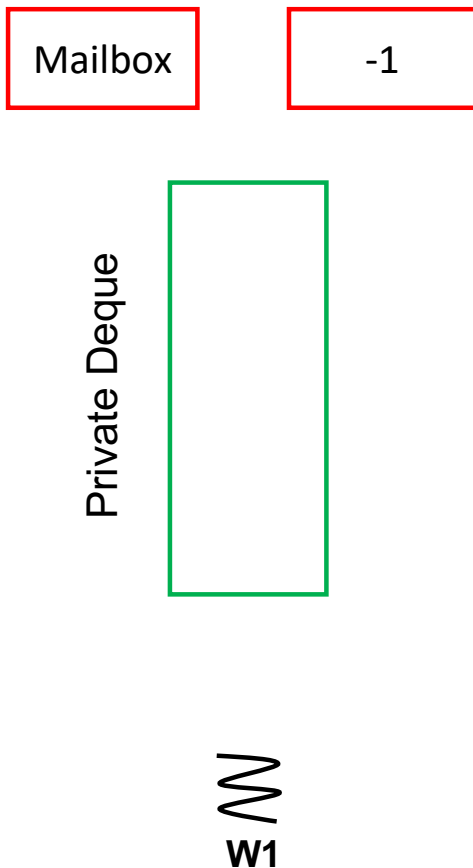
IIT Delhi

vivekk@iiitd.ac.in

Today's Class

- ➔ ● Alternative dequeues (contd.)
- Automatic task granularity control
- Quiz-1

Reducing Concurrent Access: Using **Private Deque**



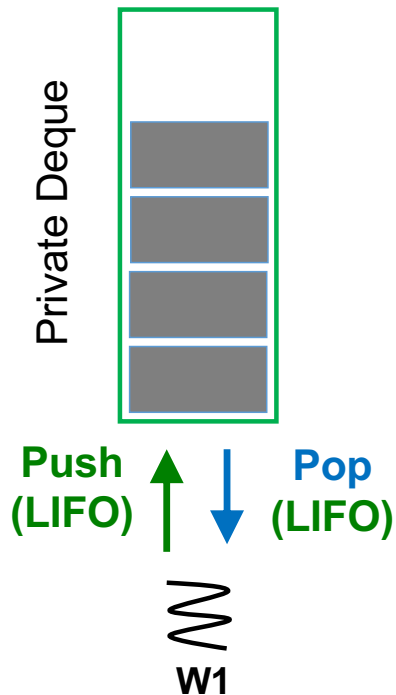
- Every worker maintains three data structures
 - A non-concurrent private deque
 - Same as the default deque, but without the support for concurrent (thread-safe) accesses
 - One mailbox
 - That can store one or more tasks
 - Contains a counter indicating total number of stored tasks
 - One shared counter

Paper: <https://hal.inria.fr/hal-00863028/document>

Reducing Deque Access: Using **Private Deque**

Mailbox

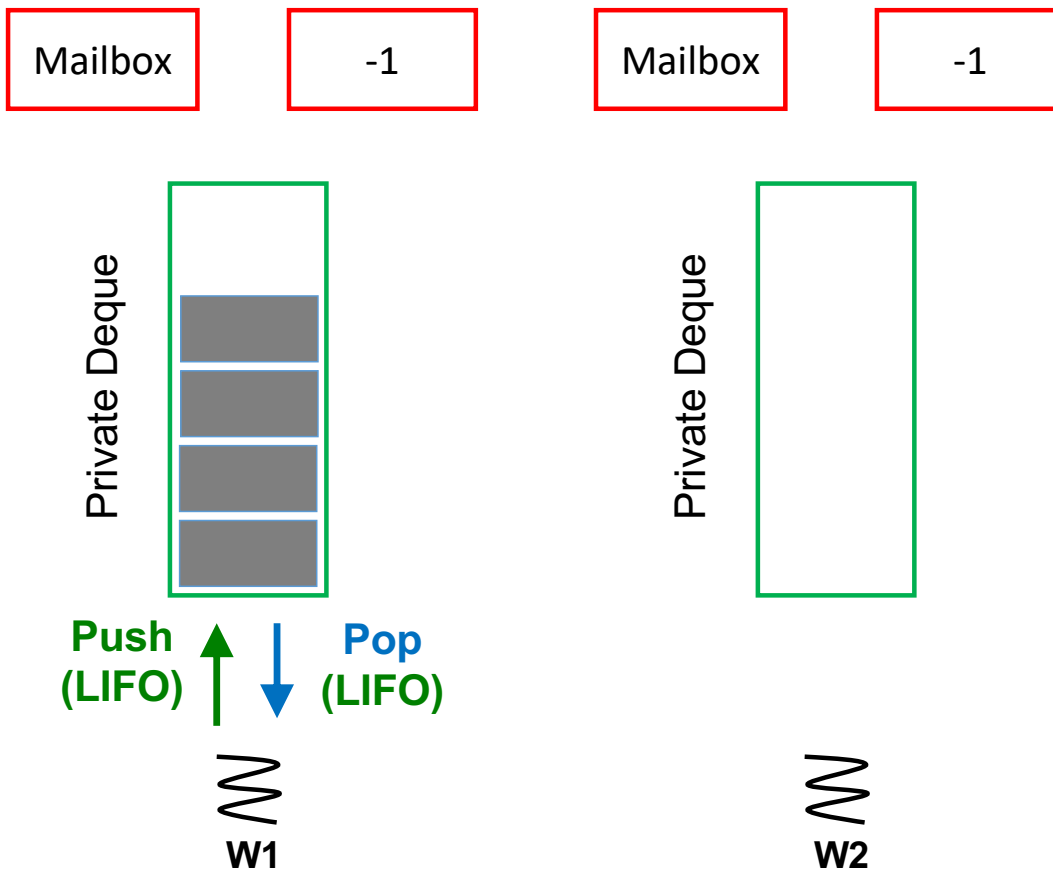
-1



- Victim
 - Push/pop tasks into its private deque

Paper: <https://hal.inria.fr/hal-00863028/document>

Reducing Deque Access: Using **Private Deque**

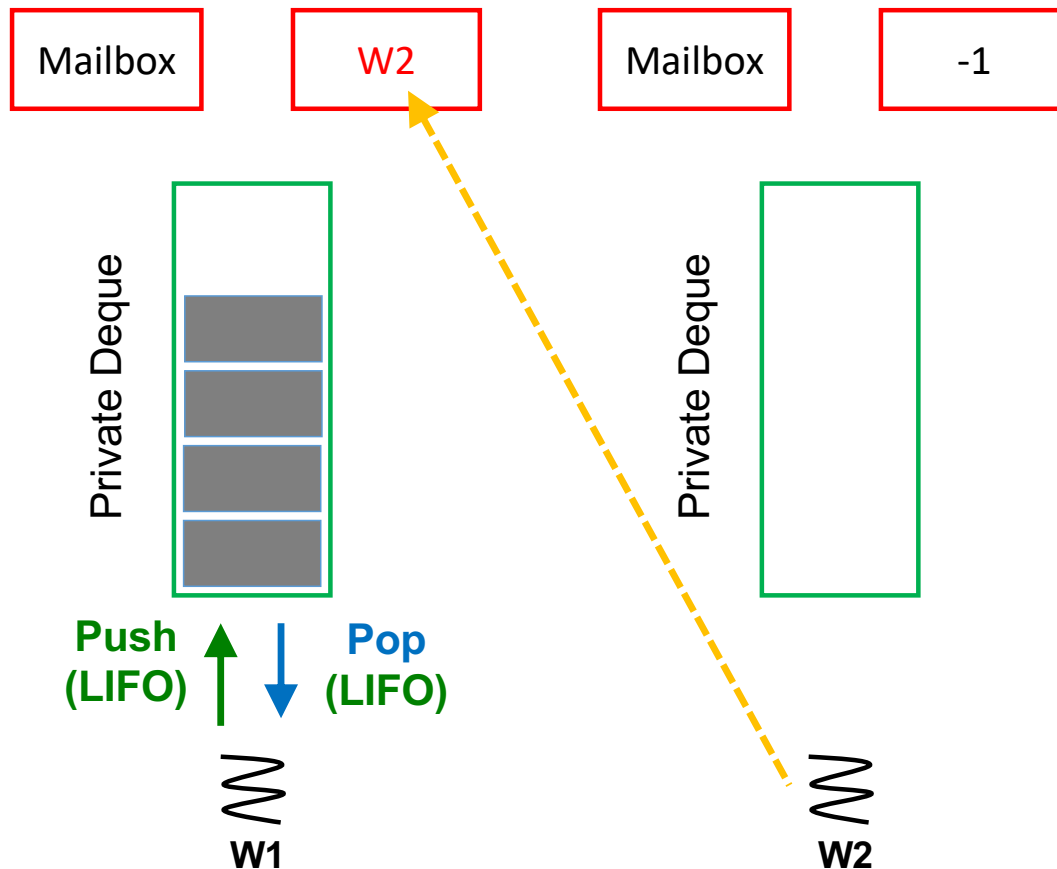


● Thief

- Selects a random victim (W1) who has items on its deque
- Checks victim deque size without any locks

Paper: <https://hal.inria.fr/hal-00863028/document>

Reducing Deque Access: Using **Private Deque**

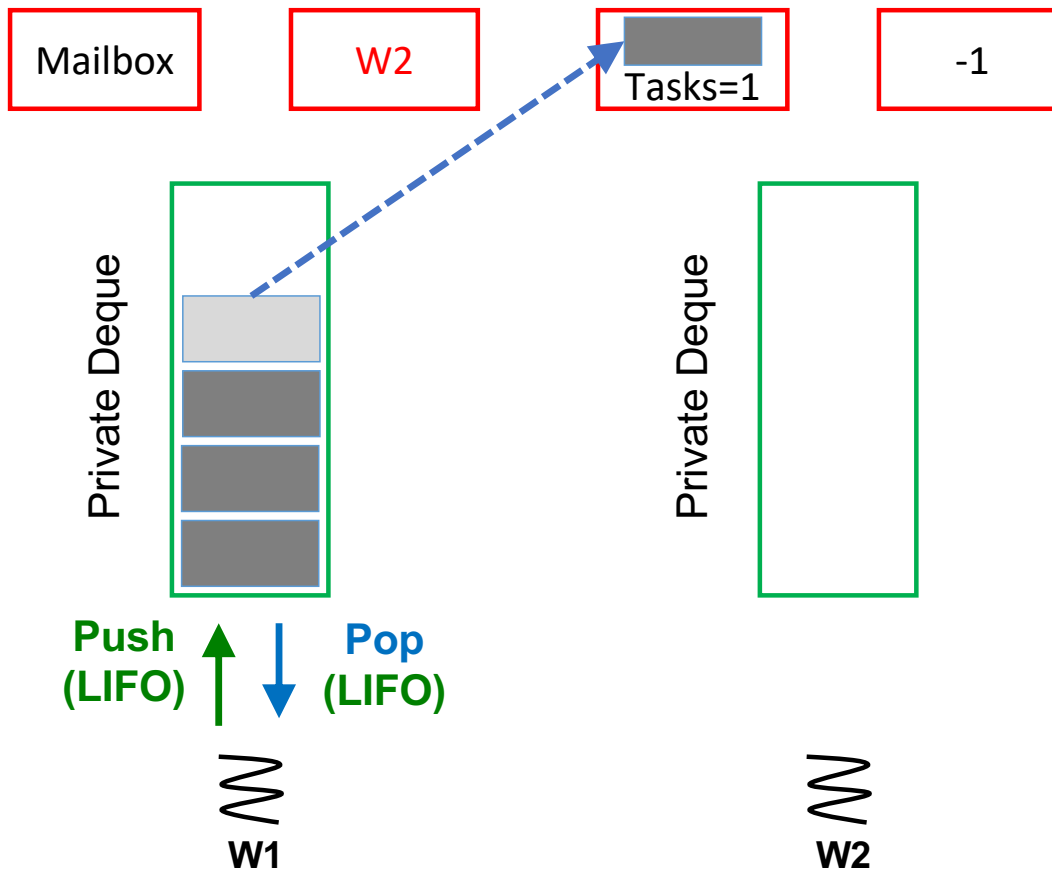


● Thief

- Record its own id inside the request box at W1 (critical section), and goes inside condition wait
- Only one thief at a time

Paper: <https://hal.inria.fr/hal-00863028/document>

Reducing Deque Access: Using **Private Deque**



● Victim

- Check its request box inside each push/pop/steal
- If tasks are available on victim's private deque
 - Pop item(s) from the head and copies it into the waiting thief's mailbox (W2)
 - Update W2's mailbox with the total number of tasks copied

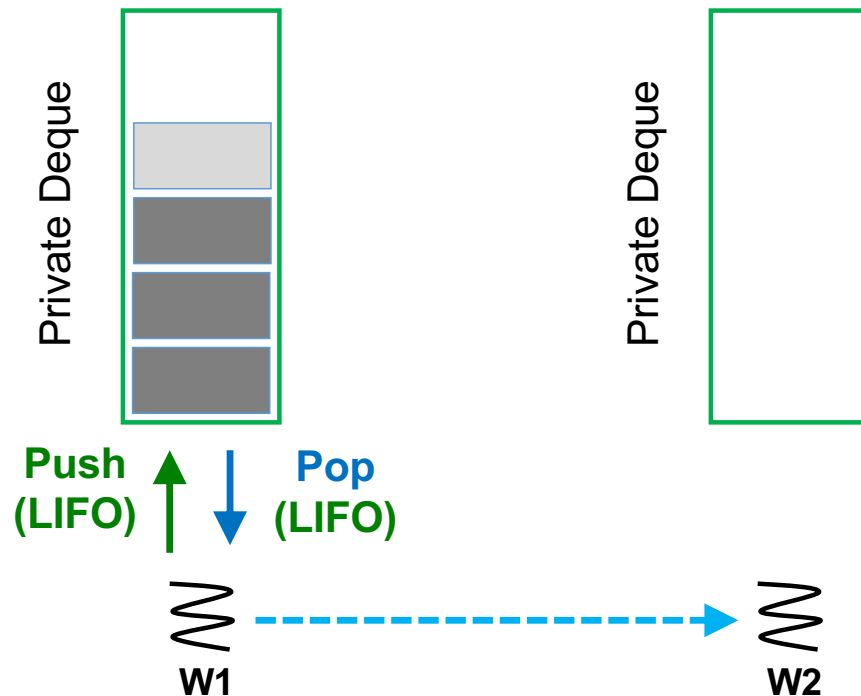
Paper: <https://hal.inria.fr/hal-00863028/document>

Reducing Deque Access: Using **Private Deque**



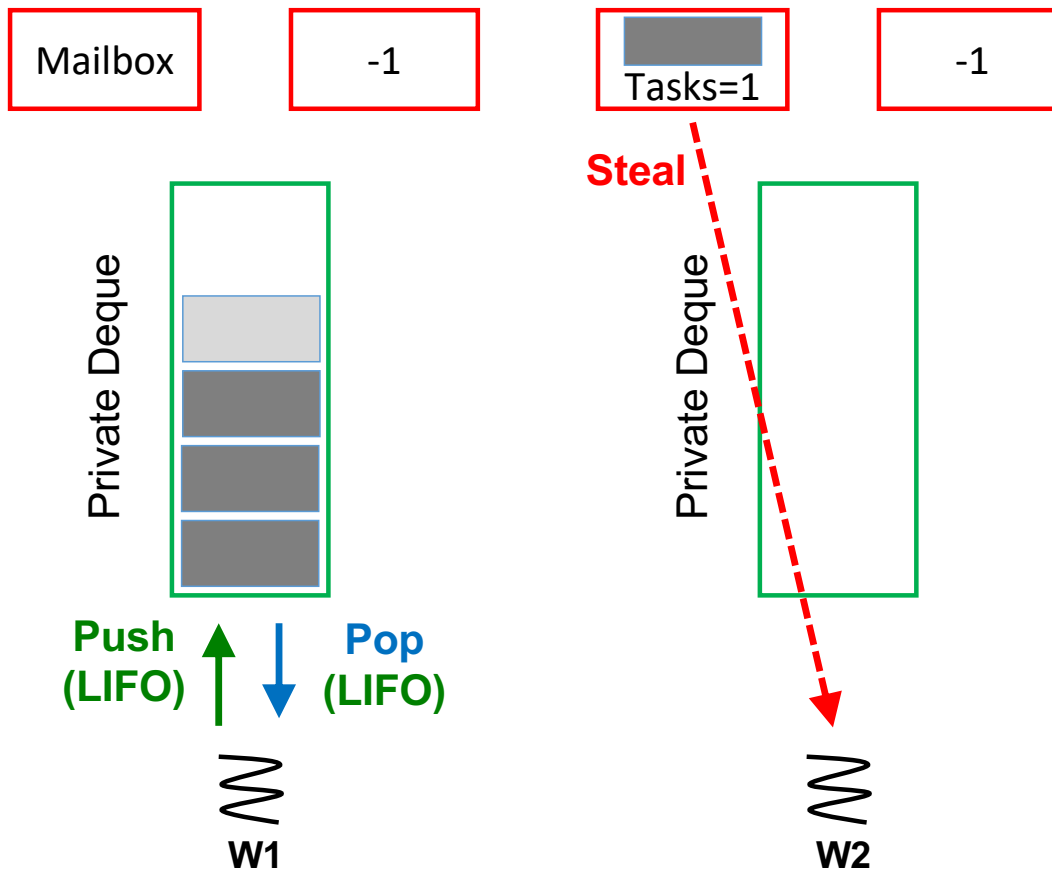
● Victim

- Clears its request box
- Signals the waiting thief W2



Paper: <https://hal.inria.fr/hal-00863028/document>

Reducing Deque Access: Using **Private Deque**



● Thief

- Unblocks after being notified by W1
- Steal tasks from its mailbox and start executing them
 - If more than one task received then extra tasks pushed to its private deque
- Failed steal attempt if it did not receive any task (i.e., if W1 ran out of tasks)

Paper: <https://hal.inria.fr/hal-00863028/document>

Private Deque using Argobots?

- You will have to create a custom scheduler instead of using the inbuilt work-stealing scheduler
 - See an example:
https://github.com/pmodels/argobots/blob/main/examples/scheduling/sched_and_pool_user.c

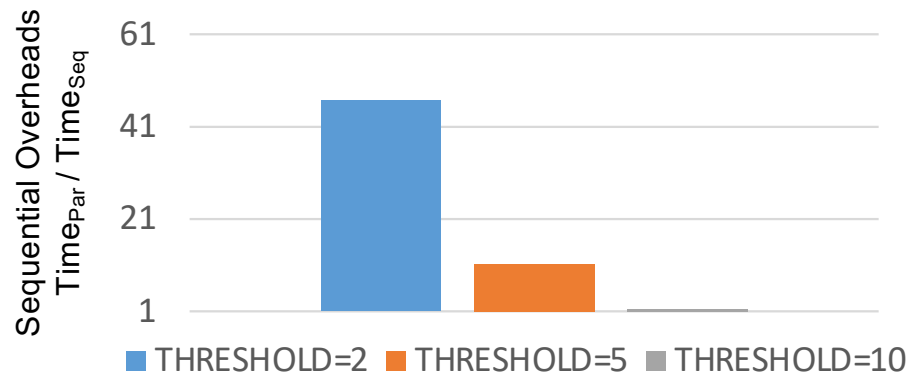
Today's Class

- Alternative dequeues (contd.)
- ➔ ● Automatic task granularity control
- Quiz-1

Task Granularity Affects Execution

```
uint64_t fib_seq(uint64_t n) {
    if(n<2) {
        return n;
    } else {
        return fib_seq(n-1) + fib_seq(n-2);
    }
}

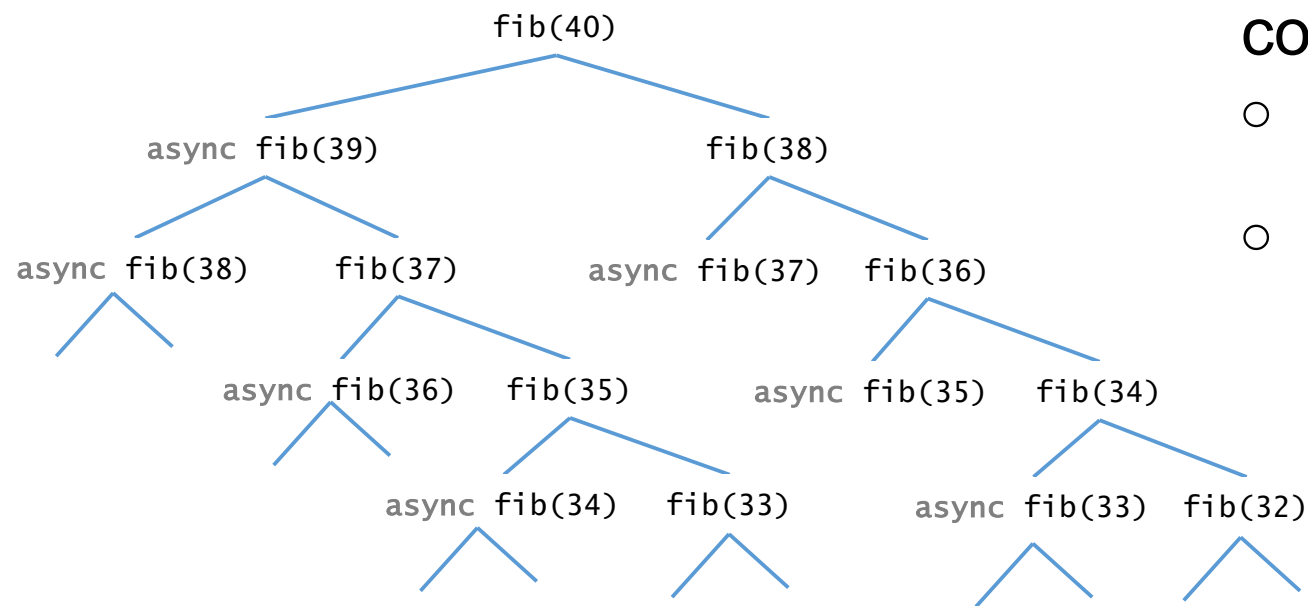
uint64_t fib(uint64_t n) {
    if(n<THRESHOLD) {
        return fib_seq(n);
    } else {
        std::future<uint64_t> f1 = std::async([](){ return fib(n-1); });
        std::future<uint64_t> f2 = std::async([](){ return fib(n-2); });
        //get will block until result is ready
        return f1.get() + f2.get();
    }
}
```



Running parallel recursive parallel Fib(40) using HCLib as its async won't launch thread unlike std::async

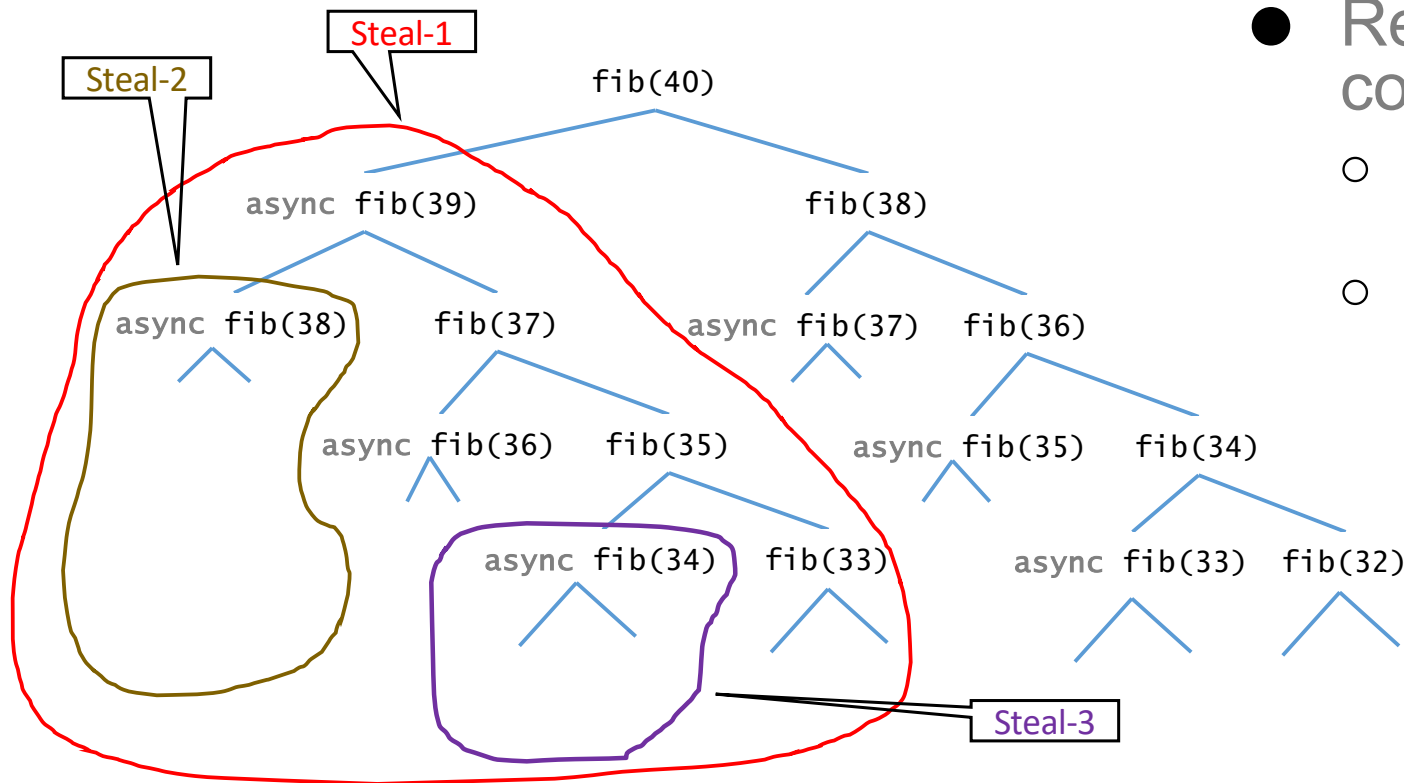
- We know concurrent dequeues have overheads, but if we want to continue using the concurrent dequeues, then how can we avoid sequential overheads?
 - By controlling task granularity
 - Neither too many tasks, nor too few!
- Options to control task granularity?
 1. Calculate Task-2 (fib of n-2) sequentially
 2. Don't create async tasks when N is less than certain threshold
 - What threshold is optimal?
 3. Use memoization
 - Is it possible for all parallel programs?

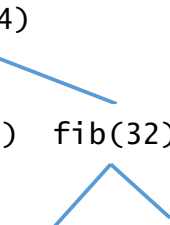
First and Foremost, Work-Stealing is Best Suited for What Kind of Applications?



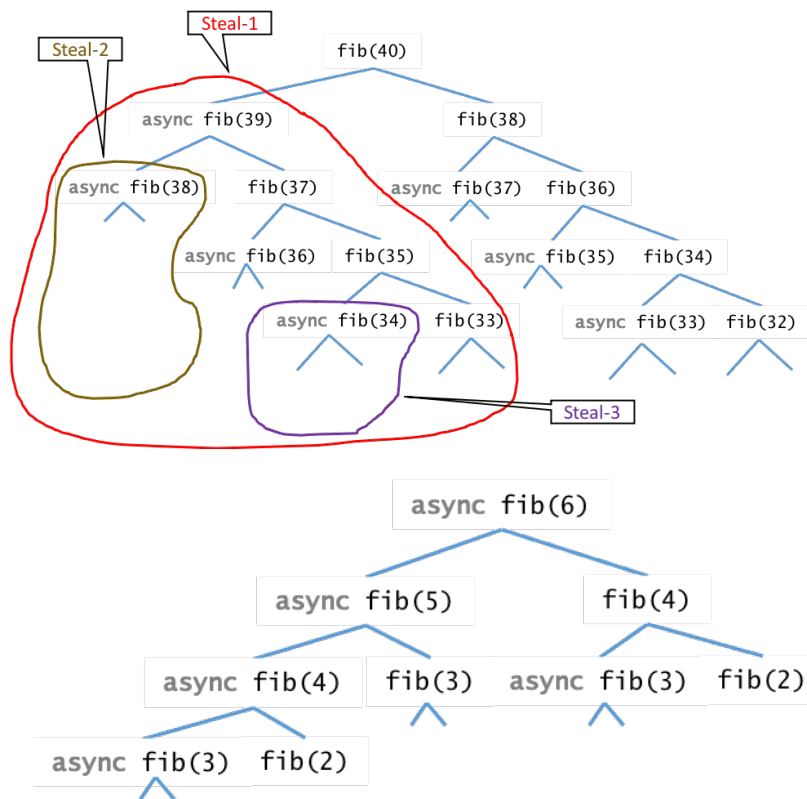
- Recursive divide-and-conquer style
 - Leads to fine granular task creation
 - **How its helpful?**
 1. Nested task creation

First and Foremost, Work-Stealing is Best Suited for What Kind of Applications?



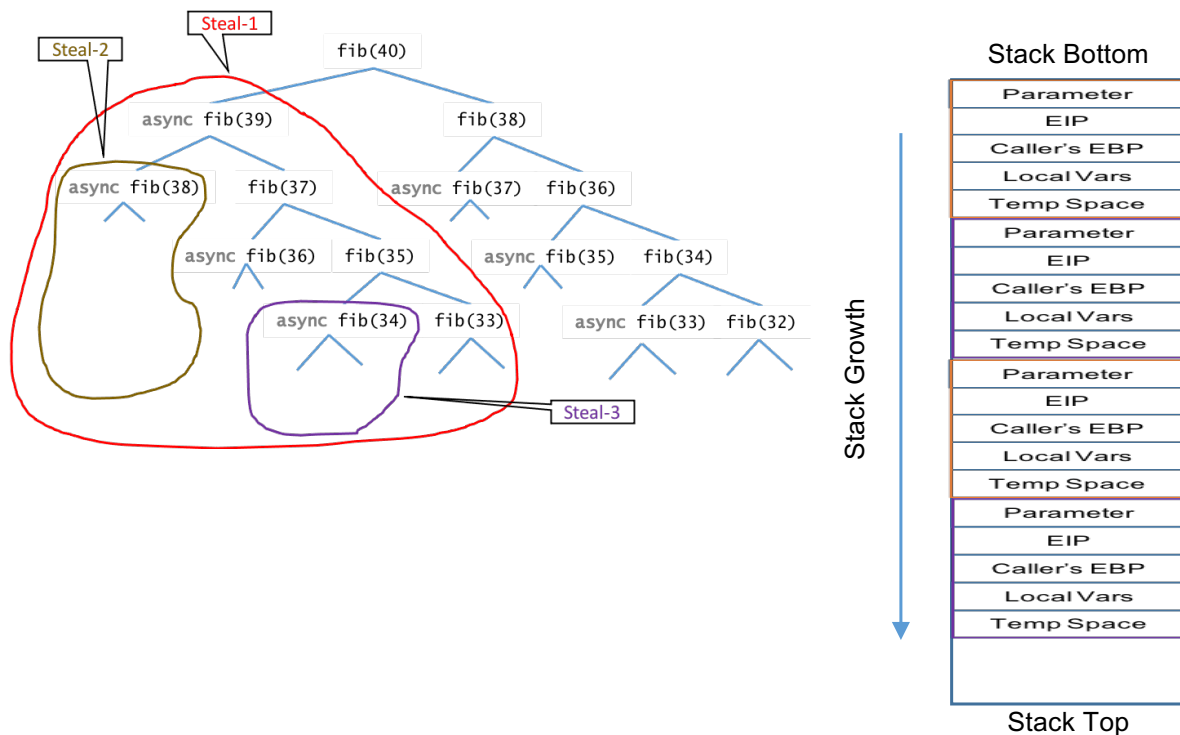
- Recursive divide-and-conquer style
 - Leads to fine granular task creation
 - How its helpful?
 1. Nested task creation
 2. Stealing an async will eventually give birth to several new asyncs at the thief
 - It will keep the thief busy and reduce steal attempts
- 

First and Foremost, Work-Stealing is Best Suited for What Kind of Applications?



- Recursive divide-and-conquer style
 - Leads to fine granular task creation
 - **Disadvantages?**
 1. Tasks created near the bottom of the tree are too small in computation, and wouldn't be able to keep a thief busy once stolen

First and Foremost, Work-Stealing is Best Suited for What Kind of Applications?



- Recursive divide-and-conquer style
 - Leads to fine granular task creation
 - **Disadvantages?**
 1. Tasks created near the bottom of the tree are too small in computation, and wouldn't be able to keep a thief busy once stolen
 2. Thread stack too deep
 - Too many context switches for moving back and forth between caller and callee stack frames (although in user space)
 - Too many context switches for moving back and forth between caller and callee stack frames (although in user space)

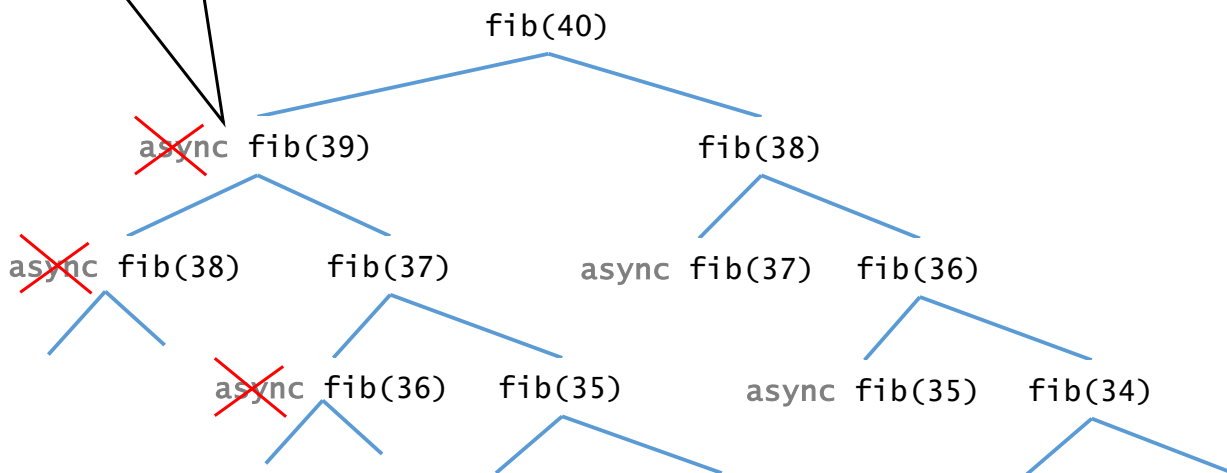
How to Avoid Those Disadvantages

1. **Tasks near the bottom of the tree are small computations**
 - Automatic granularity control
 - Stop creating new async after some “**depth**” is reached
 - Async created after that “depth” is executed sequentially
2. **Deep thread stack due to recursion**
 - Using two versions of the parallel code
 - Convert recursion into iterative call after appropriate “depth”

Solution-1: Automatic Granularity Control

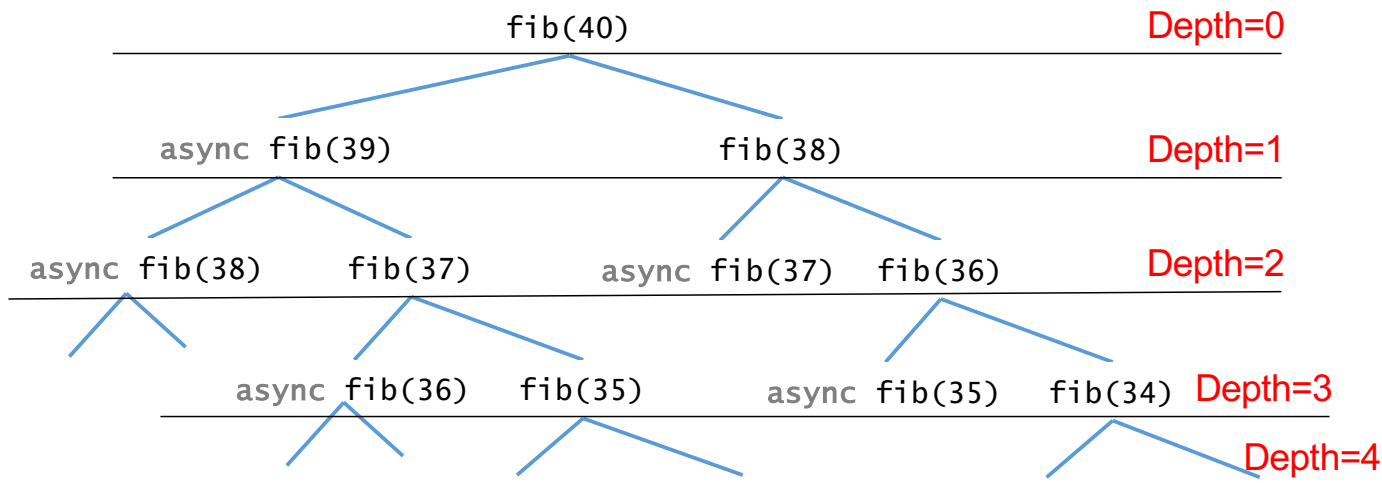
- Runtime can perform dynamic task aggregations

Aggregation of this task will not create any new async in this subtree, and the async will be executed sequentially

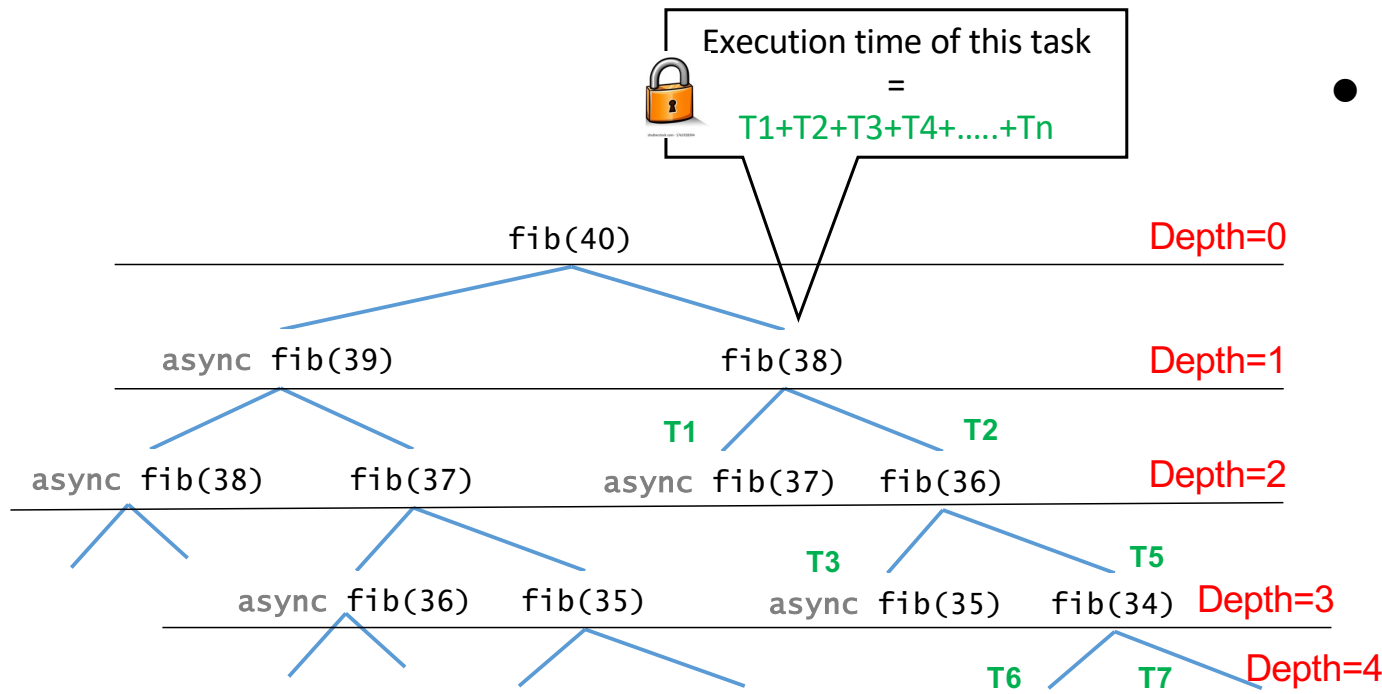


Solution-1: Automatic Granularity Control

- Runtime can perform dynamic task aggregations
- Each task keeps track of its depth in the recursion tree, and its execution time
 - Depth is stored locally inside the task



Solution-1: Automatic Granularity Control

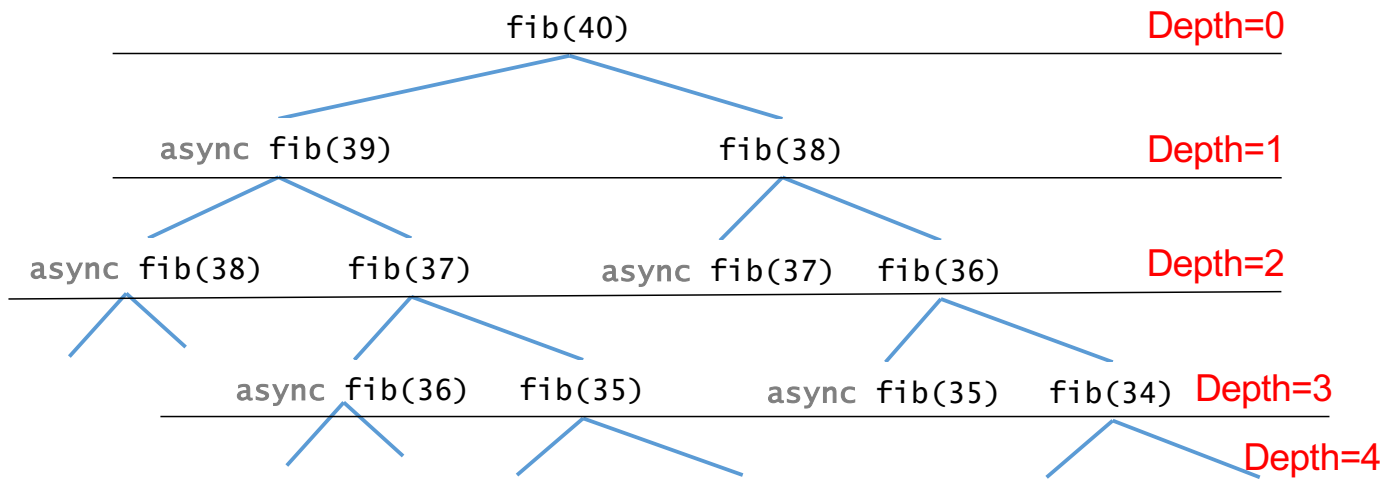


- Runtime can perform dynamic task aggregations
- Each task keeps track of its depth in the recursion tree, and its execution time
 - Depth is stored locally inside the task
- Whenever a task complete its execution, it does two things
 - It add its execution time to the parent task's execution time
 - Mutual exclusion required

Solution-1: Automatic Granularity Control



Key=0 Value=0	Key=1 Value=0	Key=2 Value=0	Key=3 Value=0	
------------------	------------------	------------------	------------------	--

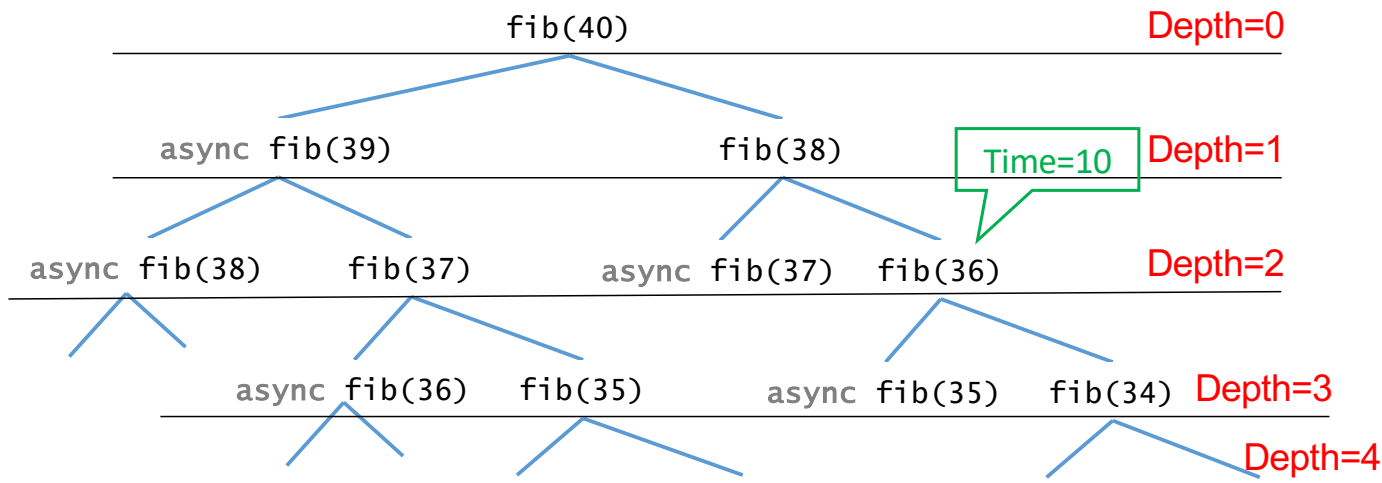


- Runtime can perform dynamic task aggregations
- Each task keeps track of its depth in the recursion tree, and its execution time
 - Depth is stored locally inside the task
- Whenever a task complete its execution, it does two things
 - It add its execution time to the parent task's execution time
 - Mutual exclusion required
 - Update the execution time at its depth in a shared global hash map (key=depth, value=time)

Solution-1: Automatic Granularity Control



Key=0 Value=0	Key=1 Value=0	Key=2 Value=10	Key=3 Value=0	
------------------	------------------	-------------------	------------------	--

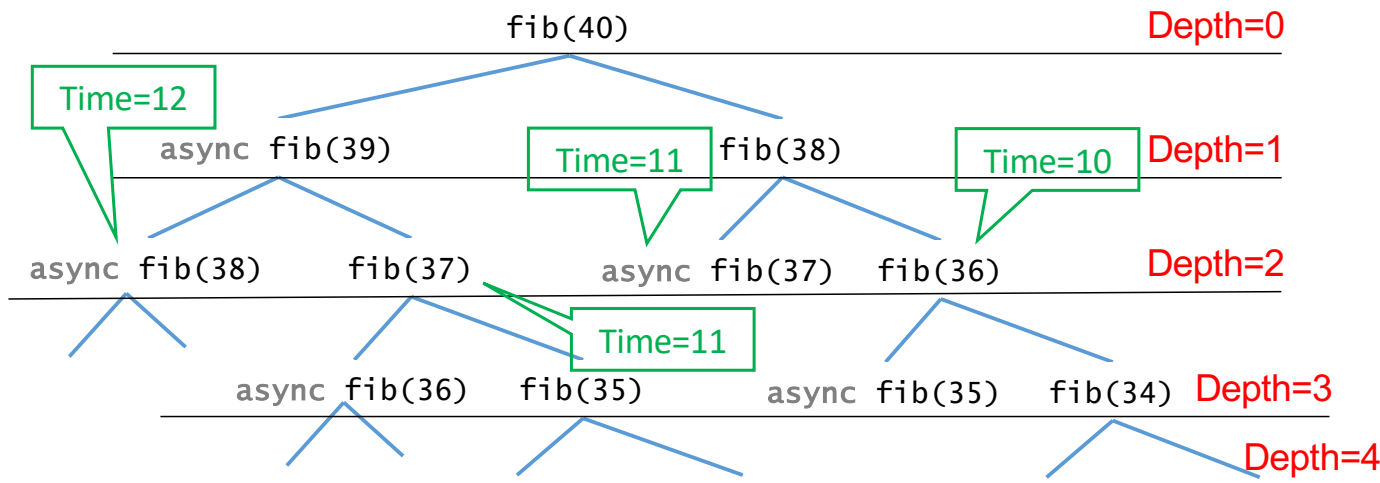


- Runtime can perform dynamic task aggregations
- Each task keeps track of its depth in the recursion tree, and its execution time
 - Depth is stored locally inside the task
- Whenever a task complete its execution, it does two things
 - It add its execution time to the parent task's execution time
 - Mutual exclusion required
 - Update the execution time at its depth in a shared global hash map (key=depth, value=time)

Solution-1: Automatic Granularity Control



Key=0 Value=0	Key=1 Value=0	Key=2 Value=10	Key=3 Value=0	
------------------	------------------	-------------------	------------------	--



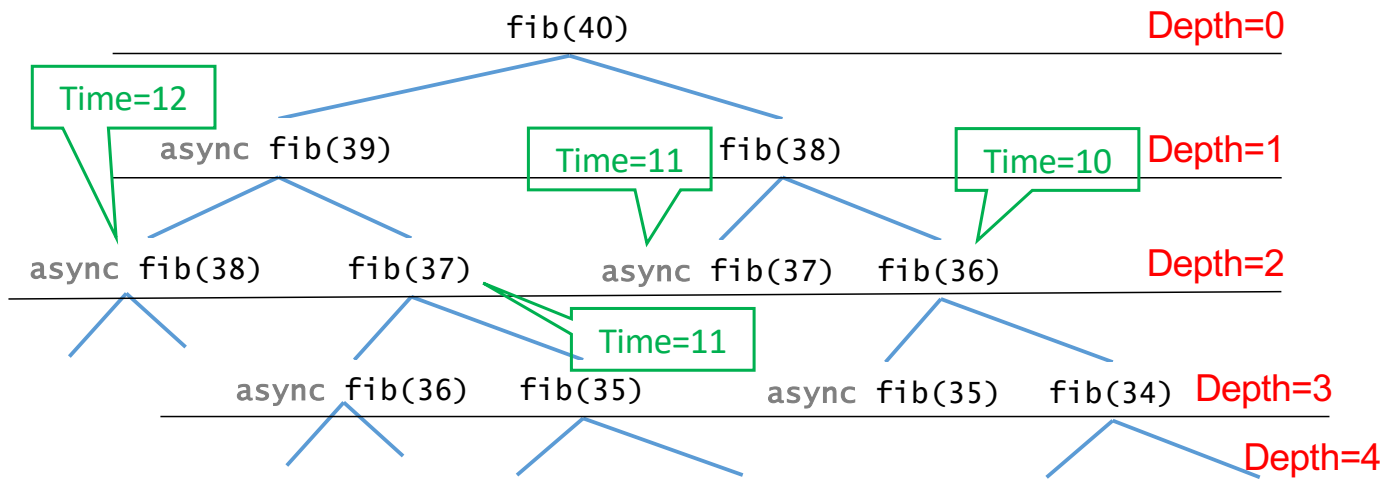
- Runtime can perform dynamic task aggregations
- Each task keeps track of its depth in the recursion tree, and its execution time
 - Depth is stored locally inside the task
- Whenever a task complete its execution, it does two things
 - It add its execution time to the parent task's execution time
 - Mutual exclusion required
 - Update the execution time at its depth in a shared global hash map (key=depth, value=time)
 - Averaging of value (time) for a given key (depth) when more than one tasks complete its execution
 - Averaging would be stopped after enough samples collected at a depth

Solution-1: Automatic Granularity Control



Key=0 Value=0	Key=1 Value=0	Key=2 Value=11	Key=3 Value=0	
------------------	------------------	-------------------	------------------	--

Average value of all time

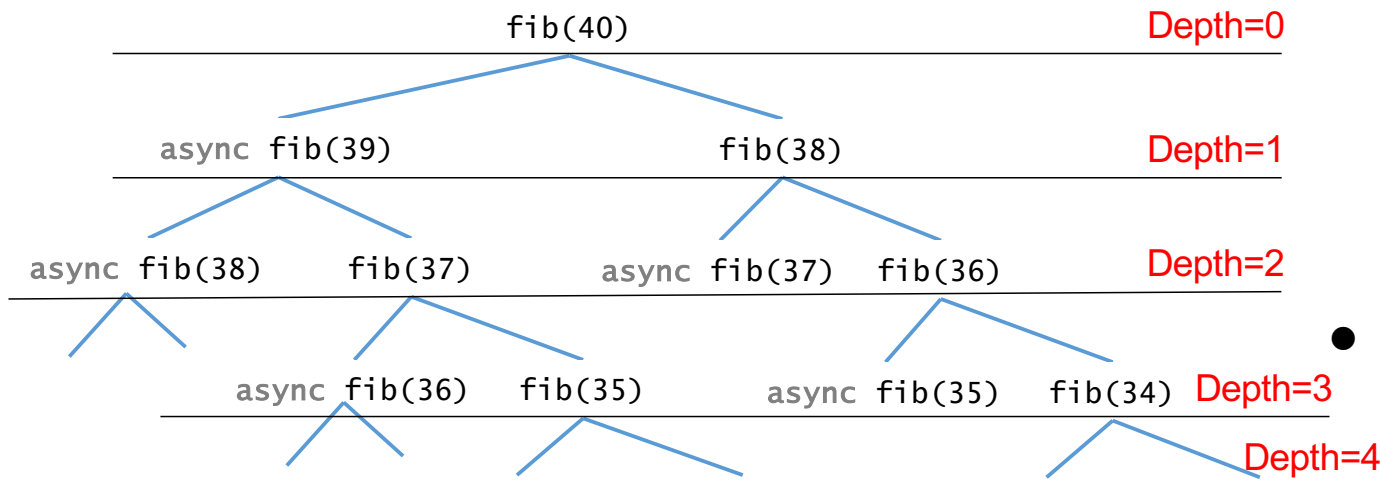


- Runtime can perform dynamic task aggregations
- Each task keeps track of its depth in the recursion tree, and its execution time
 - Depth is stored locally inside the task
- Whenever a task complete its execution, it does two things
 - It add its execution time to the parent task's execution time
 - Mutual exclusion required
 - Update the execution time at its depth in a shared global hash map (key=depth, value=time)
 - Averaging of value (time) for a given key (depth) when more than one tasks complete its execution
 - Averaging would be stopped after enough samples collected at a depth

Solution-1: Automatic Granularity Control



Key=0 Value=14	Key=1 Value=12	Key=2 Value=11	Key=3 Value=9	
-------------------	-------------------	-------------------	------------------	--



- Runtime can perform dynamic task aggregations
- Each task keeps track of its depth in the recursion tree, and its execution time
 - Depth is stored locally inside the task
- Whenever a task complete its execution, it does two things
 - It add its execution time to the parent task's execution time
 - Mutual exclusion required
 - Update the execution time at its depth in a shared global hash map (key=depth, value=time)
 - Averaging of value (time) for a given key (depth) when more than one tasks complete its execution
 - Averaging would be stopped after enough samples collected at a depth
- Depth threshold decided based on the execution time of tasks at each depth
 - Beyond this depth threshold tasks would be aggregated

Solution-2: Using Two Versions of the Code

```
uint64_t fib(uint64_t n) {  
    if (n < 2) {  
        return n;  
    } else {  
        uint64_t x = fib(n-1);  
        uint64_t y = fib(n-2);  
        return (x + y);  
    }  
}
```



```
uint64_t fib(uint64_t n) {  
    uint64_t f1=1;  
    uint64_t f2=1;  
    uint64_t m=2;  
    while(m < n) {  
        uint64_t temp = f2+f1;  
        f1=f2;  
        f2=temp;  
        m=m+1;  
    }  
    return f2;  
}
```

- When depth threshold is reached, switch to an iterative version of the recursive algorithm
 - Most of the recursive algorithms can be converted into iterative algorithm
 - Although, asking the user to provide an iterative version is breaking the support for serial elision

There is a general format for converting tail recursion into iterative version: <https://www.baeldung.com/cs/convert-recursion-to-iteration>

Reading Materials

- Private deques
 - <https://hal.inria.fr/hal-00863028/document>
- Automatic granularity control
 - An adaptive cut-off for task parallelism, SC 2008
 - https://www.academia.edu/download/35796885/1234120839604__a36-duran.pdf
- Using multiple versions of the code
 - A static cut-off for task parallel programs, PACT 2016
 - https://www.eidos.ic.i.u-tokyo.ac.jp/~iwasaki/files/PACT2016_slides.pdf
- You may only read the implementation section and skip theorem/proofs (if any)

Next Lecture (L #08)

- Memory consistency models
- Project milestone-1 will be announced over the weekend